**Medical Coverage Policy** | Powered Exoskeleton for Ambulation in Patients with Lower-Limb Disabilities



**EFFECTIVE DATE:** 07 | 01 | 2021 **POLICY LAST UPDATED:** 03 | 15 | 2023

#### **OVERVIEW**

The goal of the powered exoskeleton is to enable people who do not have volitional movement of their lower extremities to be able to fully bear weight while standing, to walk, and to navigate stairs. The devices have the potential to restore mobility and, thus, might improve functional status, quality of life, and health status for patients with spinal cord injury, multiple sclerosis, amyotrophic lateral sclerosis, Guillain-Barré syndrome, and spina bifida.

# **MEDICAL CRITERIA**

Not applicable

## **PRIOR AUTHORIZATION**

Not applicable

# **POLICY STATEMENT**

## Medicare Advantage Plans

Use of a powered exoskeleton for ambulation in individuals with lower-limb disabilities is not covered as the evidence is insufficient to determine the effects of the technology on health outcomes.

### **Commercial Products**

Use of a powered exoskeleton for ambulation in individuals with lower-limb disabilities is considered not medically necessary as the evidence is insufficient to determine the effects of the technology on health outcomes.

### **COVERAGE**

Benefits may vary between groups and contracts. Please refer to the appropriate Benefit Booklet, Evidence of Coverage or Subscriber Agreement for not covered/not medically necessary benefits/coverage.

### BACKGROUND

An exoskeleton is an external structure with joints and links that might be regarded as wearable robots designed around the shape and function of the human body. A powered exoskeleton, as described in this evidence review, consists of an exoskeleton-like framework worn by a person that includes a power source supplying energy for limb movement. One type of powered lower-limb exoskeleton (eg, ReWalk, Indego) provides user-initiated mobility based on postural information. Standing, walking, sitting, and stair up/down modes are determined by a mode selector on a wristband. ReWalk includes an array of sensors and proprietary algorithms that analyze body movements (eg, tilt of the torso) and manipulate the motorized leg braces. The tilt sensor is used to signal the onboard computer when to take the next step. Patients using the powered exoskeleton must be able to use their hands and shoulders with forearm crutches or a walker to maintain balance. Instructions for ambulating with ReWalk1, are to place the crutches ahead of the body, and then bend the elbows slightly, shifting weight toward the front leg, leaning toward the front leg side. The rear leg will lift slightly off of the ground and then begin to move forward. Using the crutches to straighten up will enable the rear leg to continue moving forward. The process is repeated with the other leg. To move from a seated to standing position or vice versa, the desired movement is selected by the mode selector on the wrist. There is a 5-second delay to allow the individual to shift weight (forward for sit-to-stand and slightly backward for stand-to-sit) and to place their crutches in the correct position. If the user is not in an appropriate position, a safety mechanism will be triggered. Walking can only be enabled while standing, and the weight shift must be sufficient to move the tilt sensor and offload the back leg to allow it to swing forward. Continuous ambulation is accomplished by uninterrupted shifting onto the contralateral leg. The device can be switched to standing either via the mode selector or by not shifting weight laterally for 2 seconds, which triggers the safety mechanism to stop walking. Some patients have become proficient with ReWalk by the third week of training.

# **Regulatory Status**

In 2014, ReWalk<sup>TM</sup> (ReWalk Robotics, previously Argo Medical Technologies) was granted a de novo 510(k) classification (K131798) by the FDA (Class II; FDA product code: PHL). The new classification applies to this device and substantially equivalent devices of this generic type. ReWalk<sup>TM</sup> is the first external, powered, motorized orthosis (powered exoskeleton) used for medical purposes that is placed over a person's paralyzed or weakened limbs for the purpose of providing ambulation. De novo classification allows novel products with moderate- or low-risk profiles and without predicates that would ordinarily require premarket approval as a Class III device to be down-classified in an expedited manner and brought to market with a special control as a Class II device.

The ReWalk<sup>TM</sup> is intended to enable individuals with spinal cord injury at levels T7 to L5 to perform ambulatory functions with supervision of a specially trained companion in accordance with the user assessment and training certification program. The device is also intended to enable individuals with spinal cord injury at levels T4 to T6 to perform ambulatory functions in rehabilitation institutions in accordance with the user assessment and training certification program. The ReWalk<sup>TM</sup> is not intended for sports or stair climbing.

Candidates for the device should have the following characteristics:

- Hands and shoulders can support crutches or a walker
- Healthy bone density
- Skeleton does not suffer from any fractures
- Able to stand using a device such as a standing frame
- In general good health
- Height is between 160 cm and 190 cm (5'3" to 6'2")
- Weight does not exceed 100 kg (220 lb).

In 2019, the ReWalk ReStore<sup>TM</sup>, a lightweight, wearable, exo-suit, was approved for rehabilitation of individuals with lower limb disabilities due to stroke.

In 2016, Indego® (Parker Hannifin) was cleared for marketing by the FDA through the 510(k) process (K152416). The FDA determined that this device was substantially equivalent to existing devices, citing ReWalk<sup>TM</sup> as a predicate device. Indego® is "intended to enable individuals with spinal cord injury at levels T7 to L5 to perform ambulatory functions with supervision of a specially trained companion." Indego® has also received marketing clearance for use in rehabilitation institutions.

In 2016, Ekso<sup>TM</sup> and Ekso GT<sup>TM</sup>(Ekso Bionics<sup>®</sup> Inc) were cleared for marketing by the FDA through the 510(k) process (K143690). The ReWalk<sup>TM</sup> was the predicate device. Ekso is intended to perform ambulatory functions in rehabilitation institutions under the supervision of a trained physical therapist for the following populations with upper extremity motor function of at least 4/5 in both arms: individuals with hemiplegia due to stroke; individuals with spinal cord injuries at levels T4 to L5; individuals with spinal cord injuries at levels of C7 to T3.

In 2017, HAL for Medical Use (Lower Limb Type) (CYBERDYNE Inc.) was cleared for marketing by the FDA through the 510(k) process (K171909). The ReWalk<sup>TM</sup> was the predicate device. The HAL is intended to

be used inside medical facilities while under trained medical supervision for individuals with spinal cord injury at levels C4 to L5 (ASIA C, ASIA D) and T11 to L5 (ASIA A with Zones of Partial Preservation, ASIA B)

In 2020, Keeogo<sup>TM</sup> (B-Temia) exoskeleton was cleared for marketing by the FDA through the 510(k) process (K201539). The Honda Walking Assist Device was the predicate device. Keeogo is intended for use in stroke patients in rehabilitation settings.

# FDA product code: PHL.

For individuals who have lower-limb disabilities who receive a powered exoskeleton, the evidence includes 1 systematic review,1 randomized controlled trial (RCT), 1 randomized cross-over study, and 1 case series describing community use. Relevant outcomes are functional outcomes, quality of life, and treatment-related morbidity. At the present, evaluation of exoskeletons is limited to small studies primarily performed in institutional settings with patients who have spinal cord injury. These studies have assessed the user's ability to perform, under close supervision, standard tasks such as the Timed Up & Go test, 6-minute walk test, and 10meter walk test. A recent systematic review included these studies and qualitatively described the effects of powered exoskeletons on walking and on secondary health conditions. However, lack of high-quality studies and heterogeneity of outcome measures precluded the ability to make general conclusions. Evidence on the use of powered exoskeletons in the community or home setting is even more limited. A recent RCT compared quality of life measures in patients with spinal cord injury using in-home powered exoskeleton plus wheelchair versus wheelchair alone, and reported similar results between both groups. In addition, 1 randomized, openlabel cross-over study and a case series in patients with multiple sclerosis and spinal cord injury, respectively, assessed use of powered exoskeletons in the outpatient setting. Although these small studies indicate powered exoskeletons may be used safely in the outpatient setting, these devices require significant training, and their efficacy has been minimally evaluated. Further evaluation of users' safety with these devices under regular conditions, including the potential to trip and fall, is necessary. Additional studies, particularly high-quality RCTs, are needed to determine the benefits of these devices both inside and outside of the institutional setting. The evidence is insufficient to determine that the technology results in an improvement in the net health outcome.

# CODING

# Medicare Advantage Plans and Commercial Products

The following code is not covered for Medicare Advantage Plans and not medically necessary for Commercial Products:

**K1007** Bilateral hip, knee, ankle, foot device, powered, includes pelvic component, single or double upright(s), knee joints any type, with or without ankle joints any type, includes all components and accessories, motors, microprocessors, sensors

## **RELATED POLICIES**

None

# PUBLISHED

Provider Update, May 2022 Provider Update, July 2022 Provider Update, July 2021

## REFERENCES

1. Zeilig G, Weingarden H, Zwecker M, et al. Safety and tolerance of the ReWalk<sup>™</sup> exoskeleton suit for ambulation bypeople with complete spinal cord injury: a pilot study. J Spinal Cord Med. Mar 2012; 35(2): 96-101. PMID 22333043

- 2. Asselin P, Knezevic S, Kornfeld S, et al. Heart rate and oxygen demand of powered exoskeletonassisted walking inpersons with paraplegia. J Rehabil Res Dev. 2015; 52(2): 147-58. PMID 26230182
- 3. Lajeunesse V, Vincent C, Routhier F, et al. Exoskeletons' design and usefulness evidence according to a systematicreview of lower limb exoskeletons used for functional mobility by people with spinal cord injury. Disabil Rehabil AssistTechnol. Oct 2016; 11(7): 535-47. PMID 26340538
- 4. Tamburella F, Lorusso M, Tramontano M, et al. Overground robotic training effects on walking and secondary healthconditions in individuals with spinal cord injury: systematic review. J Neuroeng Rehabil. Mar 15 2022; 19(1): 27. PMID35292044
- Chun A, Asselin PK, Knezevic S, et al. Changes in bowel function following exoskeletal-assisted walking in persons withspinal cord injury: an observational pilot study. Spinal Cord. Apr 2020; 58(4): 459-466. PMID 31822808
- McIntosh K, Charbonneau R, Bensaada Y, et al. The Safety and Feasibility of Exoskeletal-Assisted Walking in AcuteRehabilitation After Spinal Cord Injury. Arch Phys Med Rehabil. Jan 2020; 101(1): 113-120. PMID 31568761
- Tsai CY, Delgado AD, Weinrauch WJ, et al. Exoskeletal-Assisted Walking During Acute Inpatient Rehabilitation Leads toMotor and Functional Improvement in Persons With Spinal Cord Injury: A Pilot Study. Arch Phys Med Rehabil. Apr 2020;101(4): 607-612. PMID 31891715
- Gagnon DH, Vermette M, Duclos C, et al. Satisfaction and perceptions of long-term manual wheelchair users with a spinalcord injury upon completion of a locomotor training program with an overground robotic exoskeleton. Disabil RehabilAssist Technol. Feb 2019; 14(2): 138-145. PMID 29256640
- 9. Guanziroli E, Cazzaniga M, Colombo L, et al. Assistive powered exoskeleton for complete spinal cord injury: correlationsbetween walking ability and exoskeleton control. Eur J Phys Rehabil Med. Apr 2019; 55(2): 209-216. PMID 30156088
- Khan AS, Livingstone DC, Hurd CL, et al. Retraining walking over ground in a powered exoskeleton after spinal cordinjury: a prospective cohort study to examine functional gains and neuroplasticity. J Neuroeng Rehabil. Nov 21 2019;16(1): 145. PMID 31752911
- Kressler J, Domingo A. Cardiometabolic Challenges Provided by Variable Assisted Exoskeletal Versus OvergroundWalking in Chronic Motor-incomplete Paraplegia: A Case Series. J Neurol Phys Ther. Apr 2019; 43(2): 128-135. PMID30883500
- 12. Kubota S, Abe T, Kadone H, et al. Hybrid assistive limb (HAL) treatment for patients with severe thoracic myelopathy due to ossification of the posterior longitudinal ligament (OPLL) in the postoperative acute/subacute phase: A clinical trial. JSpinal Cord Med. Jul 2019; 42(4): 517-525. PMID 30335588
- 13. Manns PJ, Hurd C, Yang JF. Perspectives of people with spinal cord injury learning to walk using a powered exoskeleton.J Neuroeng Rehabil. Jul 19 2019; 16(1): 94. PMID 31324256
- 14. van Dijsseldonk RB, Rijken H, van Nes IJW, et al. Predictors of exoskeleton motor learning in spinal cord injured patients.Disabil Rehabil. Jul 2021; 43(14): 1982-1988. PMID 31724882
- Alamro RA, Chisholm AE, Williams AMM, et al. Overground walking with a robotic exoskeleton elicits trunk muscle activityin people with high-thoracic motor-complete spinal cord injury. J Neuroeng Rehabil. Nov 20 2018; 15(1): 109. PMID30458839
- Bach Baunsgaard C, Vig Nissen U, Katrin Brust A, et al. Gait training after spinal cord injury: safety, feasibility and gaitfunction following 8 weeks of training with the exoskeletons from Ekso Bionics. Spinal Cord. Feb 2018; 56(2): 106-116.PMID 2910565717.
- Baunsgaard CB, Nissen UV, Brust AK, et al. Exoskeleton gait training after spinal cord injury: An exploratory study onsecondary health conditions. J Rehabil Med. Sep 28 2018; 50(9): 806-813. PMID 30183055
- 18. Cahill A, Ginley OM, Bertrand C, et al. Gym-based exoskeleton walking: A preliminary exploration of non-ambulatory end-user perspectives. Disabil Health J. Jul 2018; 11(3): 478-485. PMID 29500092
- 19. Chang SH, Afzal T, Berliner J, et al. Exoskeleton-assisted gait training to improve gait in individuals with spinal cord injury:a pilot randomized study. Pilot Feasibility Stud. 2018; 4: 62. PMID 29556414
- 20. Escalona MJ, Brosseau R, Vermette M, et al. Cardiorespiratory demand and rate of perceived exertion during overgroundwalking with a robotic exoskeleton in long-term manual wheelchair users

with chronic spinal cord injury: A cross-sectionalstudy. Ann Phys Rehabil Med. Jul 2018; 61(4): 215-223. PMID 29371106

- 21. Gagnon DH, Escalona MJ, Vermette M, et al. Locomotor training using an overground robotic exoskeleton in long-termmanual wheelchair users with a chronic spinal cord injury living in the community: Lessons learned from a feasibility studyin terms of recruitment, attendance, learnability, performance and safety. J Neuroeng Rehabil. Mar 01 2018; 15(1): 12.PMID 29490678
- Juszczak M, Gallo E, Bushnik T. Examining the Effects of a Powered Exoskeleton on Quality of Life and SecondaryImpairments in People Living With Spinal Cord Injury. Top Spinal Cord Inj Rehabil. 2018; 24(4): 336-342. PMID 30459496
- Ramanujam A, Cirnigliaro CM, Garbarini E, et al. Neuromechanical adaptations during a robotic powered exoskeletonassisted walking session. J Spinal Cord Med. Sep 2018; 41(5): 518-528. PMID 28427305
- Ramanujam A, Momeni K, Husain SR, et al. Mechanisms for improving walking speed after longitudinal powered roboticexoskeleton training for individuals with spinal cord injury. Annu Int Conf IEEE Eng Med Biol Soc. Jul 2018; 2018: 2805-2808. PMID 30440984
- 25. Sale P, Russo EF, Scarton A, et al. Training for mobility with exoskeleton robot in spinal cord injury patients: a pilot study.Eur J Phys Rehabil Med. Oct 2018; 54(5): 745-751. PMID 29517187

----- CLICK THE ENVELOPE ICON BELOW TO SUBMIT COMMENTS

This medical policy is made available to you for informational purposes only. It is not a guarantee of payment or a substitute for your medical judgment in the treatment of your patients. Benefits and eligibility are determined by the member's subscriber agreement or member certificate and/or the employer agreement, and those documents will supersede the provisions of this medical policy. For information on member-specific benefits, call the provider call center. If you provide services to a member which are determined to not be medically necessary (or in some cases medically necessary services which are non-covered benefits), you may not charge the member for the services unless you have informed the member and they have agreed in writing in advance to continue with the treatment at their own expense. Please refer to your participation agreement(s) for the applicable provisions. This policy is current at the time of publication; however, medical practices, technology, and knowledge are constantly changing. BCBSRI reserves the right to review and revise this policy for any reason and at any time, with or without notice. Blue Cross & Blue Shield of Rhode Island is an independent licensee of the Blue Cross and Blue Shield Association.